





SBA
Research

The Private Cloud within Your Car

Containers, Podman and Kubernetes in your automotive products?

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K8s plugins: Kubectl your Tesla



Savithru Lokanath · Follow

3 min read · Apr 1, 2020

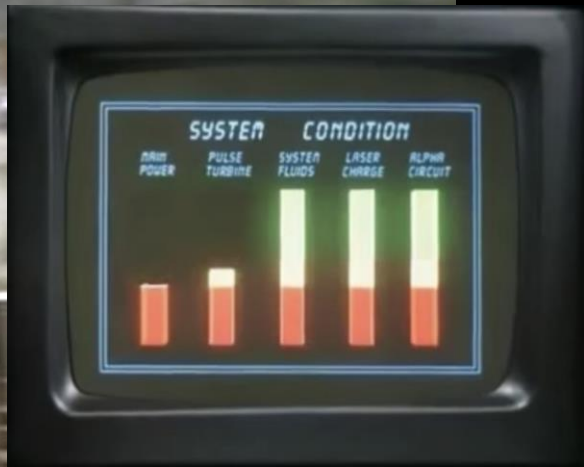


5



Fig1. Kubectl plugins

... is this safe?



Images: Knight Rider, Universal Television

Car Architecture and Ecosystem

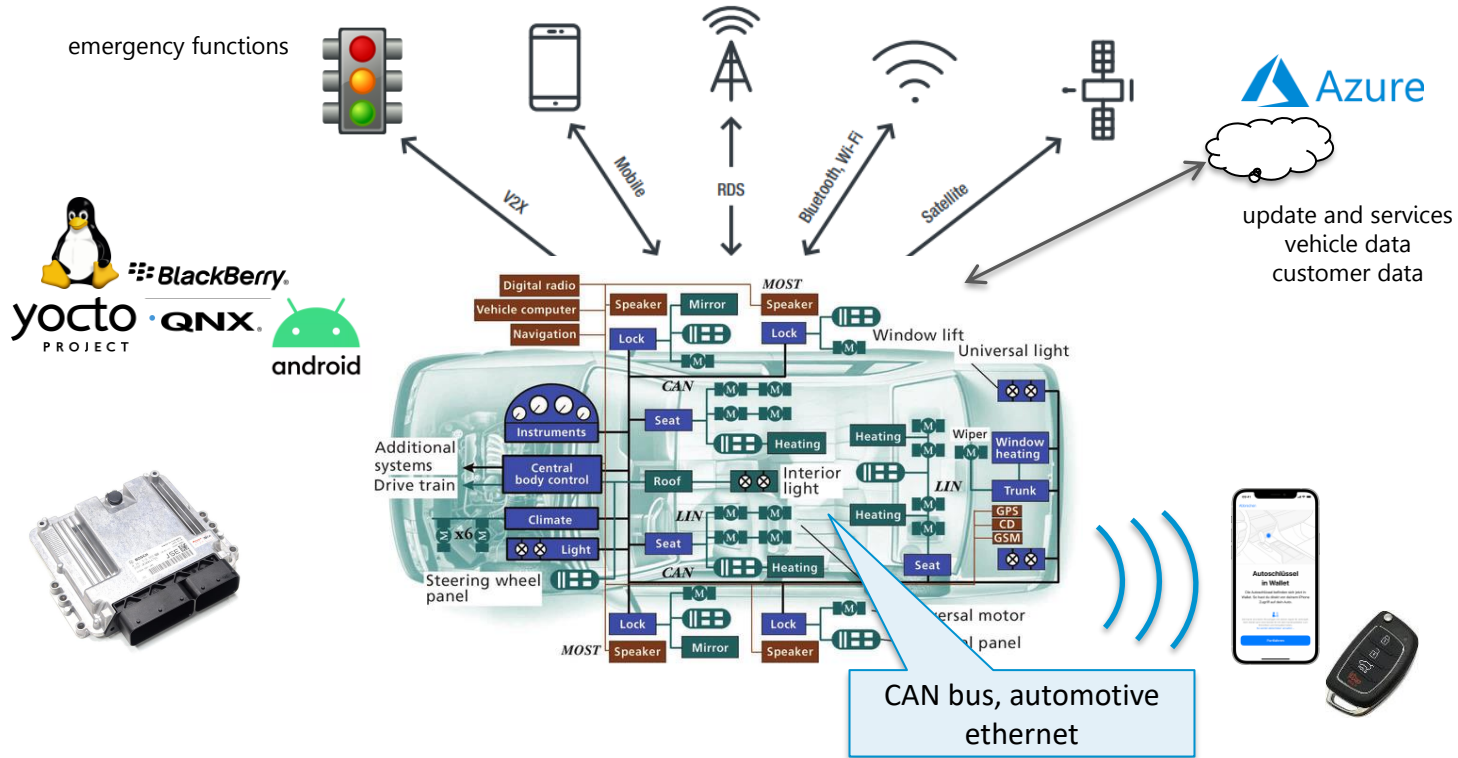
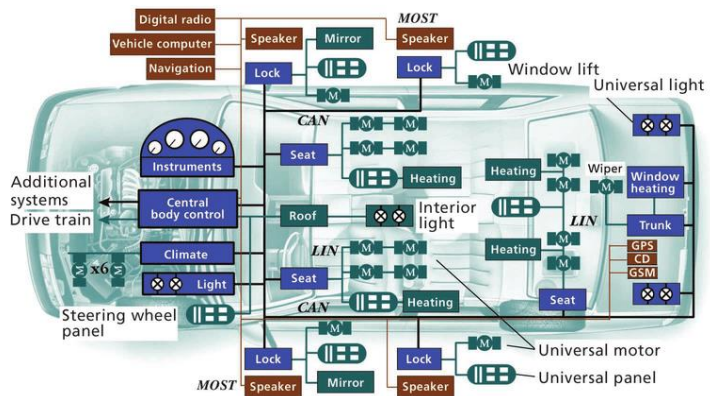


Image original: https://www.researchgate.net/figure/One-subset-of-a-modern-vehicles-network-architecture-showing-the-trend-toward_fig1_2955571



```

49|ms | ID | data ... < can0 # l=20 h=100 t=500 slots=67 >
00100 | 151 | 00 E0 80 60 | ...
00099 | 35B | 00 32 0C 80 00 3E 0E E3 .2...>..
00199 | 367 | A0 00 00 27 7F 00 02 00 | ...'....
00199 | 369 | FC 00 26 40 10 00 00 00 | ..&@....
00099 | 3C3 | 85 81 00 00 80 40 21 B9 | .....@!.
00099 | 3E1 | 12 00 26 0C 7E 32 82 00 | ..&~2..
01997 | 484 | 37 94 90 82 13 45 28 63 | 7....E(c
00799 | 485 | 07 0C 10 18 D9 C2 27 65 | ..... 'e
01799 | 486 | B6 AE DE 72 FF C4 07 CE | ...r....
00047 | 531 | 00 00 80 80 | ....
00100 | 555 | E8 F9 7B 01 32 10 04 63 | ..{.2..c
00498 | 571 | AF 00 00 00 00 00 | .....
00298 | 58C | 10 81 00 00 26 10 00 02 | ....&...
01001 | 5A1 | C1 89 A7 17 65 80 70 00 | ....e.p.
41996 | 5A3 | 30 20 58 10 46 3F 93 0C | 0 X.F?..
00199 | 5B5 | 0C 03 00 00 00 00 0F | .....
01009 | 63C | 3B CF 05 | ;..
01000 | 65D | 92 65 A9 A1 76 BB F0 07 | .e..v...
00199 | 65F | 02 56 35 30 31 33 30 36 | .V501306
00999 | 66C | 3C 52 05 00 | <R..
00990 | 66F | 3A CF 00 | :..
00999 | 67D | 3C 8F 00 | <..
02000 | 6DA | 32 82 03 00 0A 00 03 00 | 2.....
00440 | 6DB | 30 5A 03 | 0Z,
00999 | 6DC | 32 D0 64 | 2.d

```


Example: AutoSAR, Platform, Chip, Software



between 70 and 100 ECUs being installed in every modern vehicle

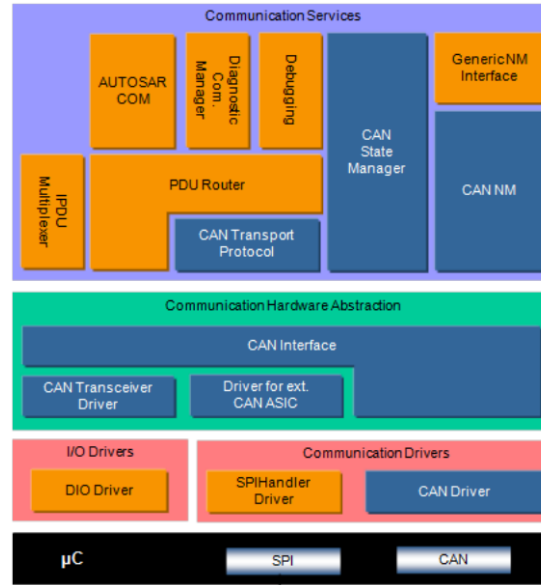
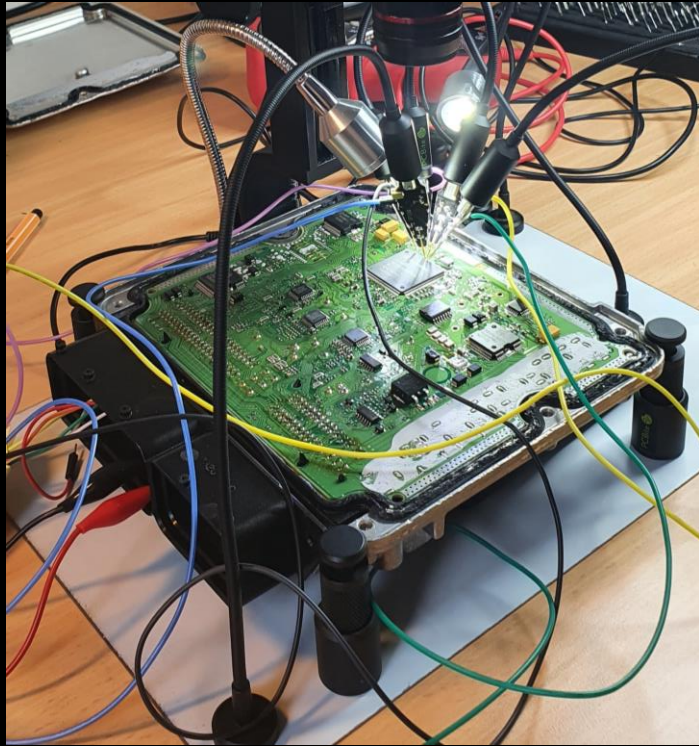
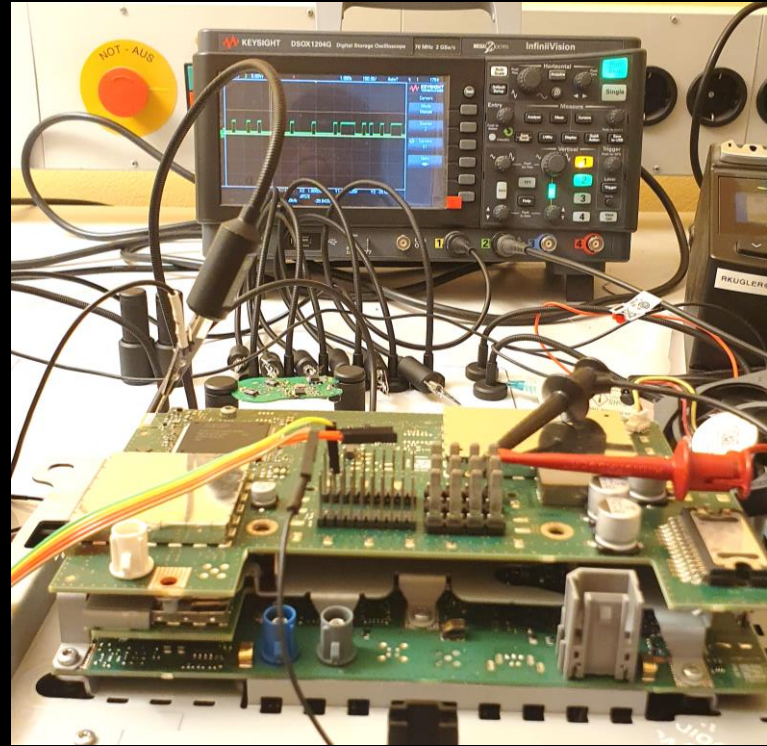


Image: Specification of CAN Interface AUTOSAR CP Release 4.3.1, p11

Electronic Control Units (opened)

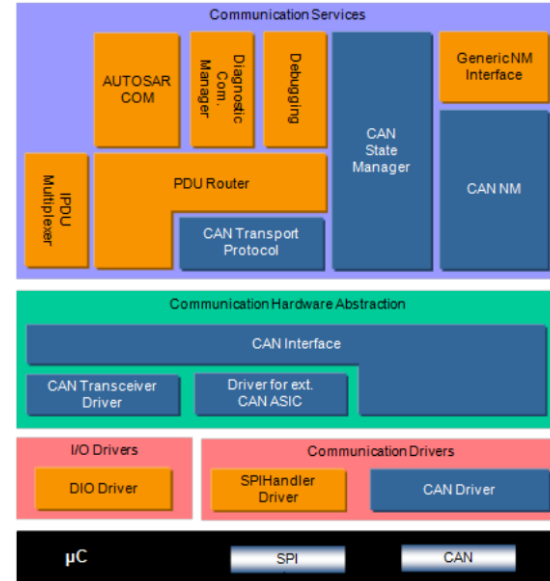
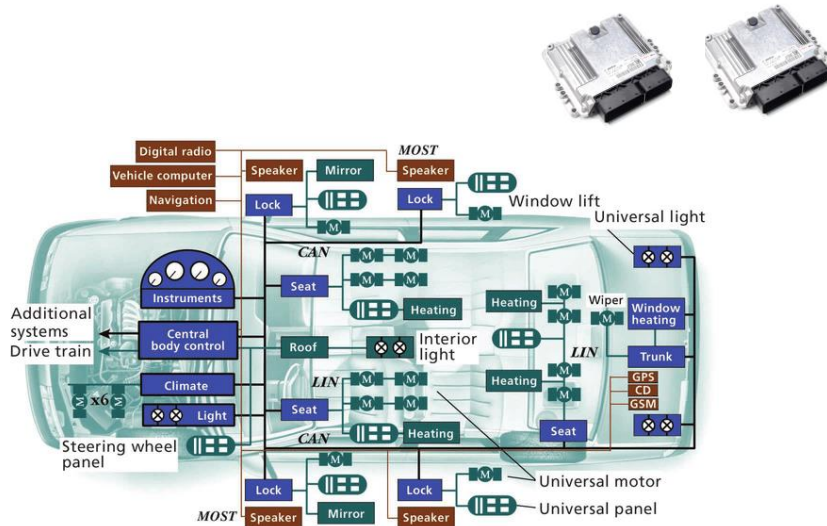


JTAG access on the PCB



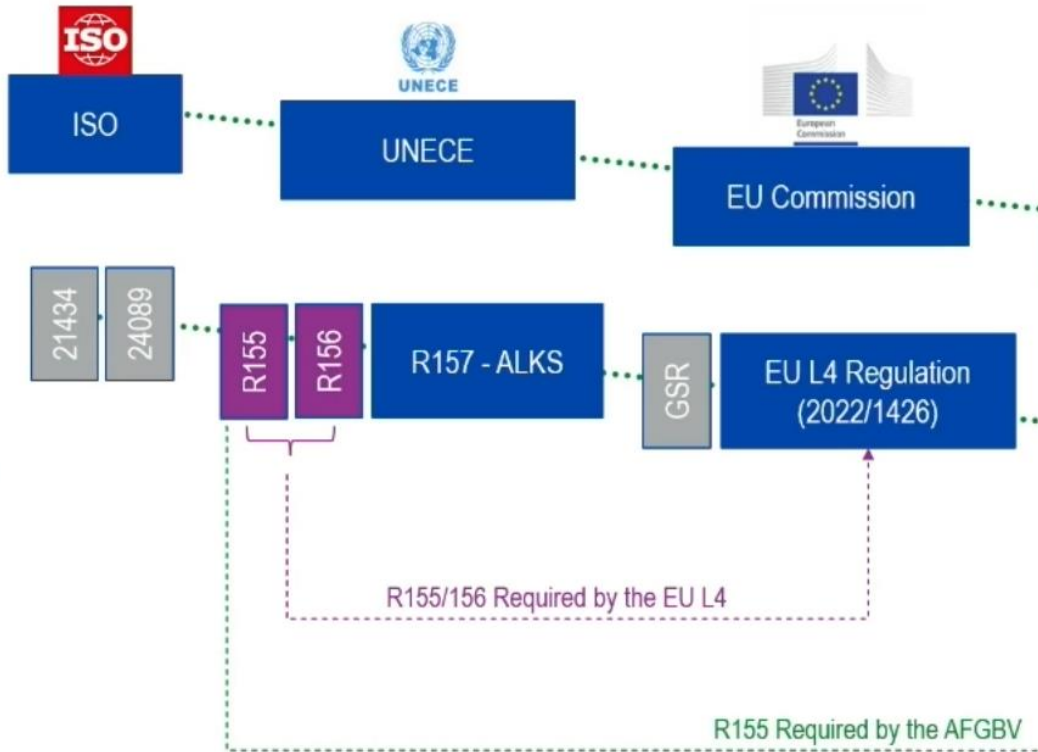
CAN access + on-board console via UART

How to maintain/update/configure hundreds of ECUs?



ISO 24089:2023

Road vehicles — Software update engineering



Abstract

[Preview](#)

This document specifies requirements and recommendations for software update engineering for road vehicles on both the organizational and the project level.

This document is applicable to road vehicles whose software can be updated.

The requirements and recommendations in this document apply to vehicles, vehicle systems, ECUs, infrastructure, and the assembly and deployment of software update packages after the initial development.

This document is applicable to organizations involved in software update engineering for road vehicles. Such organizations can include vehicle manufacturers, suppliers, and their subsidiaries or partners.

This document establishes a common understanding for communicating and managing activities and responsibilities among organizations and related parties.

The development of software for vehicle functions, except for software update engineering, is outside the scope of this document.

Finally, this document does not prescribe specific technologies or solutions for software update engineering.

General information

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Number of pages : 24

The road to AV appl

Running containers in cars

October 19, 2022

Pierre-Yves Chibon, Daniel J Walsh, Alexander Larsson

[< Back to all posts](#)

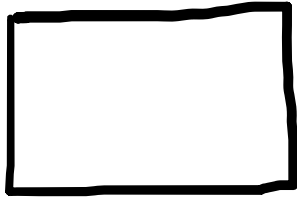
Tags: [Containers](#)

A little over a year ago, Red Hat [announced](#) its intention to collaborate with the automotive industry to help drive the transition to software-defined vehicles (SDVs). In May 2022, this intention became concrete with Red Hat and General Motors [announcing their collaboration](#) to help trailblaze SDVs at the edge. Our goal is to produce a base operating system to run all sorts of in-vehicle software for safety-critical use cases as well as non-safety ones.

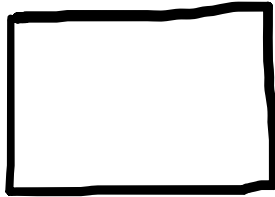
Containers have become the de facto standard in the wider IT industry, and they are front and center in the vision of the [software-defined vehicle](#), allowing for applications to be isolated, providing more flexibility for developers and deployment, and generally allowing for faster innovation. Red Hat leads the work on containers in the cloud, and now it's time to take that expertise to the automotive industry. <https://www.redhat.com/en/blog/running-containers-cars>

Functions in application containers

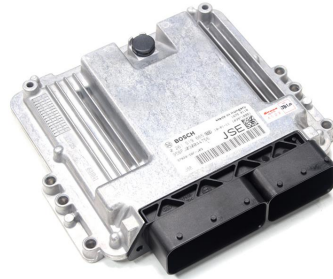
infotainment
app



seat
heating



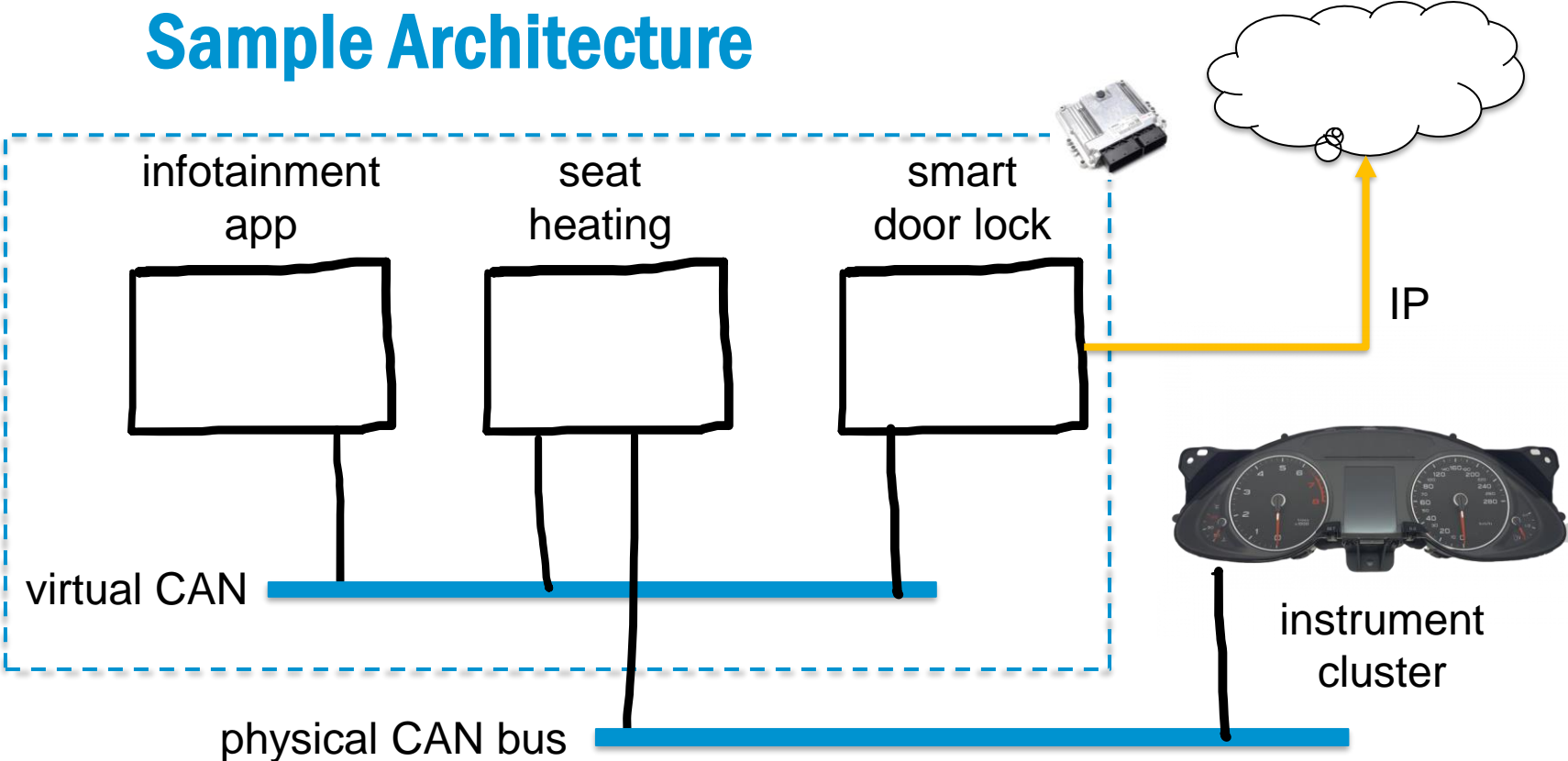
smart
door lock



(safety certified) Linux

```
(sba@automotive-security) - [~/kitt]  
$
```

Sample Architecture



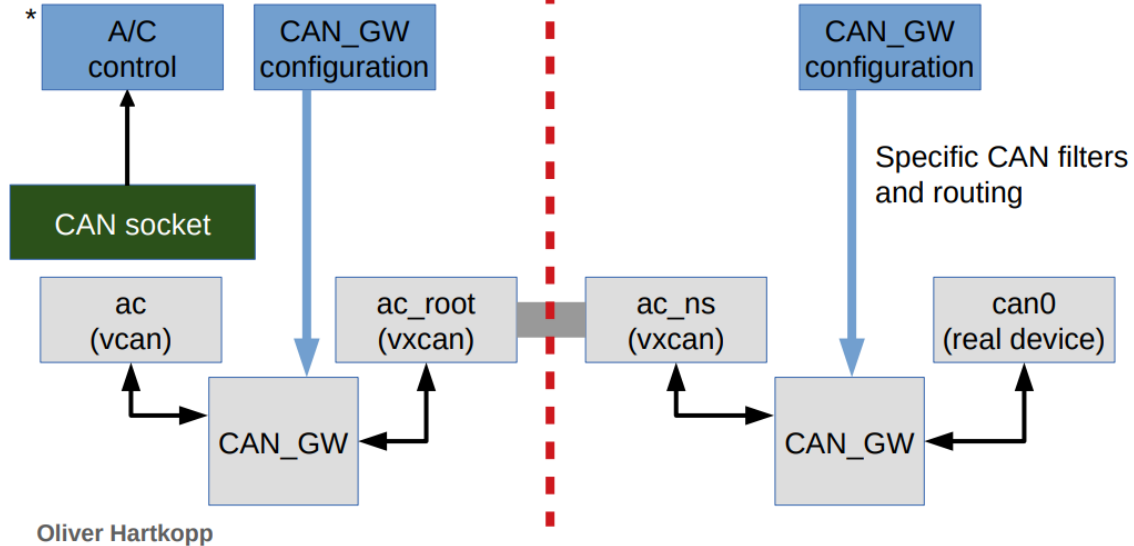
CAN and Containers, Automotive Grade Linux

VXCAN interfaces just forward; without local echo (IFF_ECHO)!

To support multiple* applications in a namespace use `vcan` via `CAN_GW` there

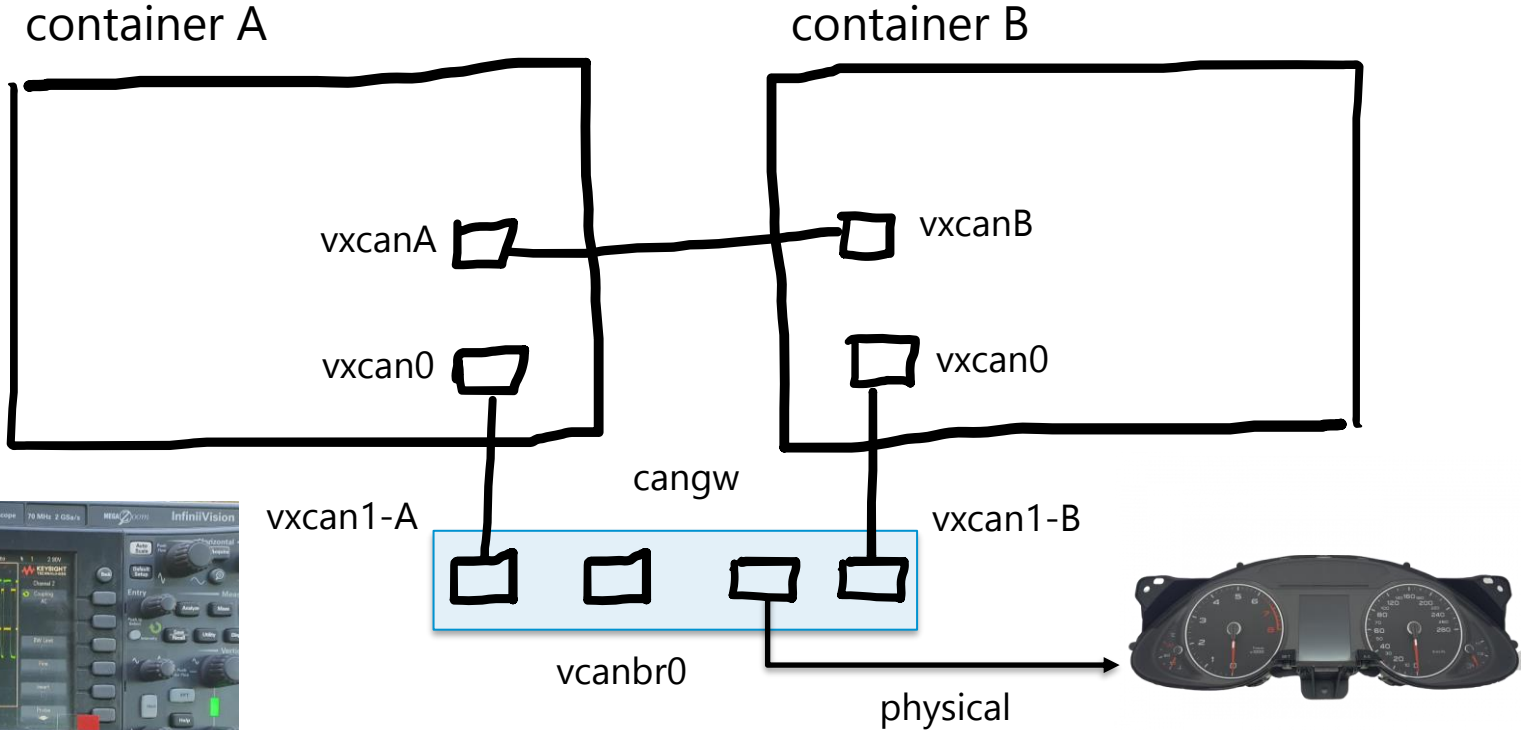
application namespace(s)

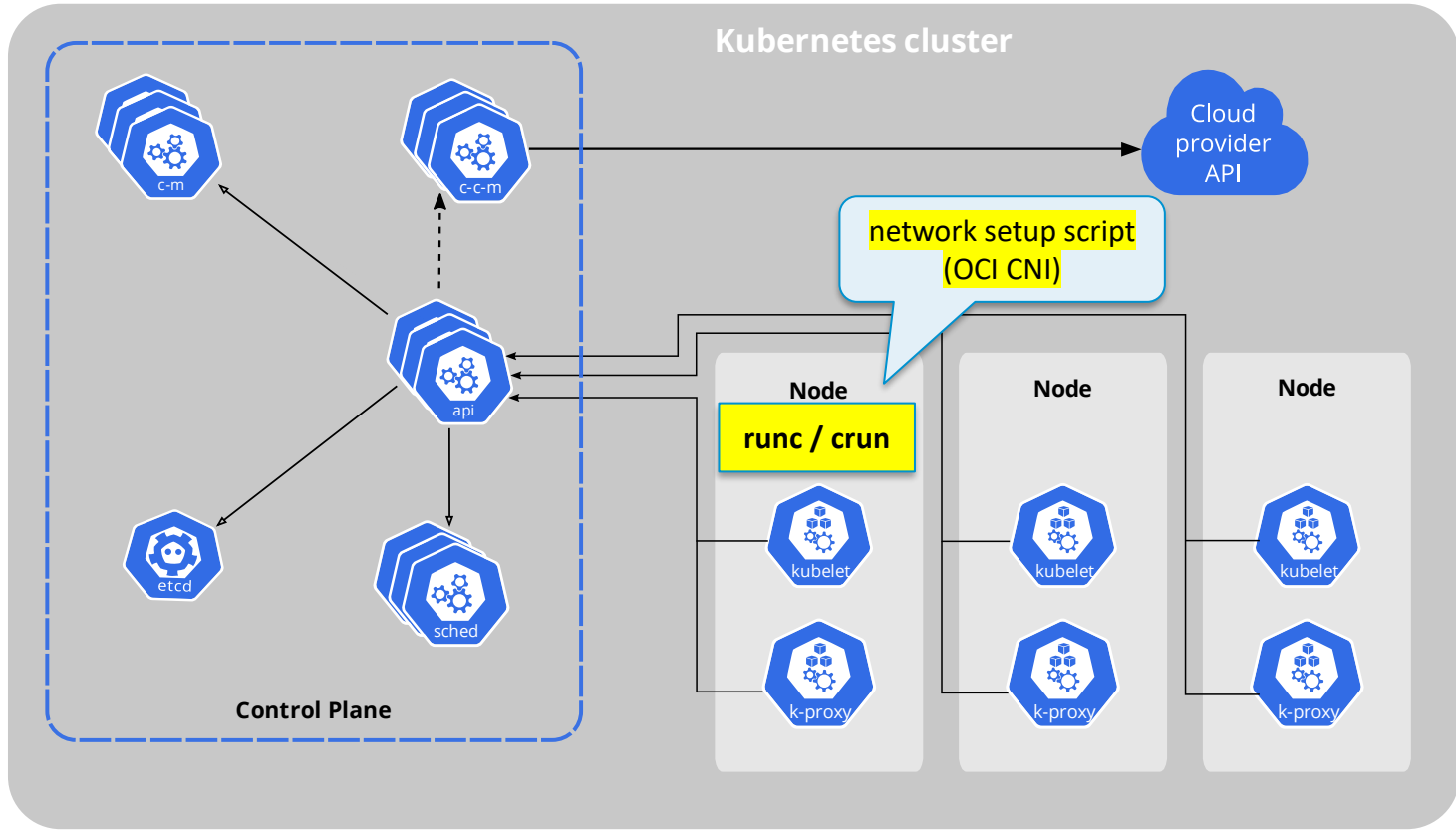
init/root/default/global namespace












https://wiki.automotivelinux.org/_media/agl-distro/agl2018-socketcan.pdf

Routing and Network namespaces (ethernet)





- API server 
- Cloud controller manager (optional) 
- Controller manager 
- etcd (persistence store) 
- kubelet 
- kube-proxy 
- Scheduler 
- Control plane 
- Node 



CNI

CNI - the Container Network Interface

What is CNI? [↗](#)

CNI (*Container Network Interface*), a [Cloud Native Computing Foundation](#) library for writing plugins to configure network interfaces in Linux containers. CNI concerns itself only with network connectivity of containers. A container is deleted. Because of this focus, CNI has a wide range of implementations.

As well as the [specification](#), this repository contains the Go source code, [applications](#) and an [example command-line tool](#) for executing CNI plugins and a template for making new plugins.

The template code makes it straight-forward to create a CNI plugin. It also makes a good framework for creating a new container network interface.

Here are the recordings of two sessions that the CNI maintainers held:

- [Introduction to CNI](#)
- [CNI deep dive](#)

```
11 # check if process is running (debug)
12 ps $containerpid || exit 1
13
14 # set up a vcan bridge, all containers terminate there (like a d
15 ip link show $scanbridgename
16 if [ $? -ne 0 ] ; then
17     ip link add name $scanbridgename type vcan
18     ip link set $scanbridgename up
19 fi
20
21 ip link add $vxcanname_container type vxcan peer name $vxcanname_
22 ip link set $vxcanname_host up
23 ip link set $vxcanname_container netns $containerpid
24
25 # set up and rename to vxcan0 (container namespace)
26 nsenter -n -t $containerpid ip link set name vxcan0 dev $vxcanname_
27 nsenter -n -t $containerpid ip link set vxcan0 up
28
29 # set up a bridge (gw) between can bridge and container vxcan (h
30 cangw -A -s $scanbridgename -d $vxcanname_host -e
31 cangw -A -s $vxcanname_host -d $scanbridgename -e
32
33 # flow in (physical to container)
34 #cangw -A -s "$physical_can" -d "$vxcanname_host" -e
35 # flow out (container to physical)
36 #cangw -A -d "$physical_can" -s "$vxcanname_host" -e
```

```
(sba@automotive-security) - [~/kitt]  
$
```

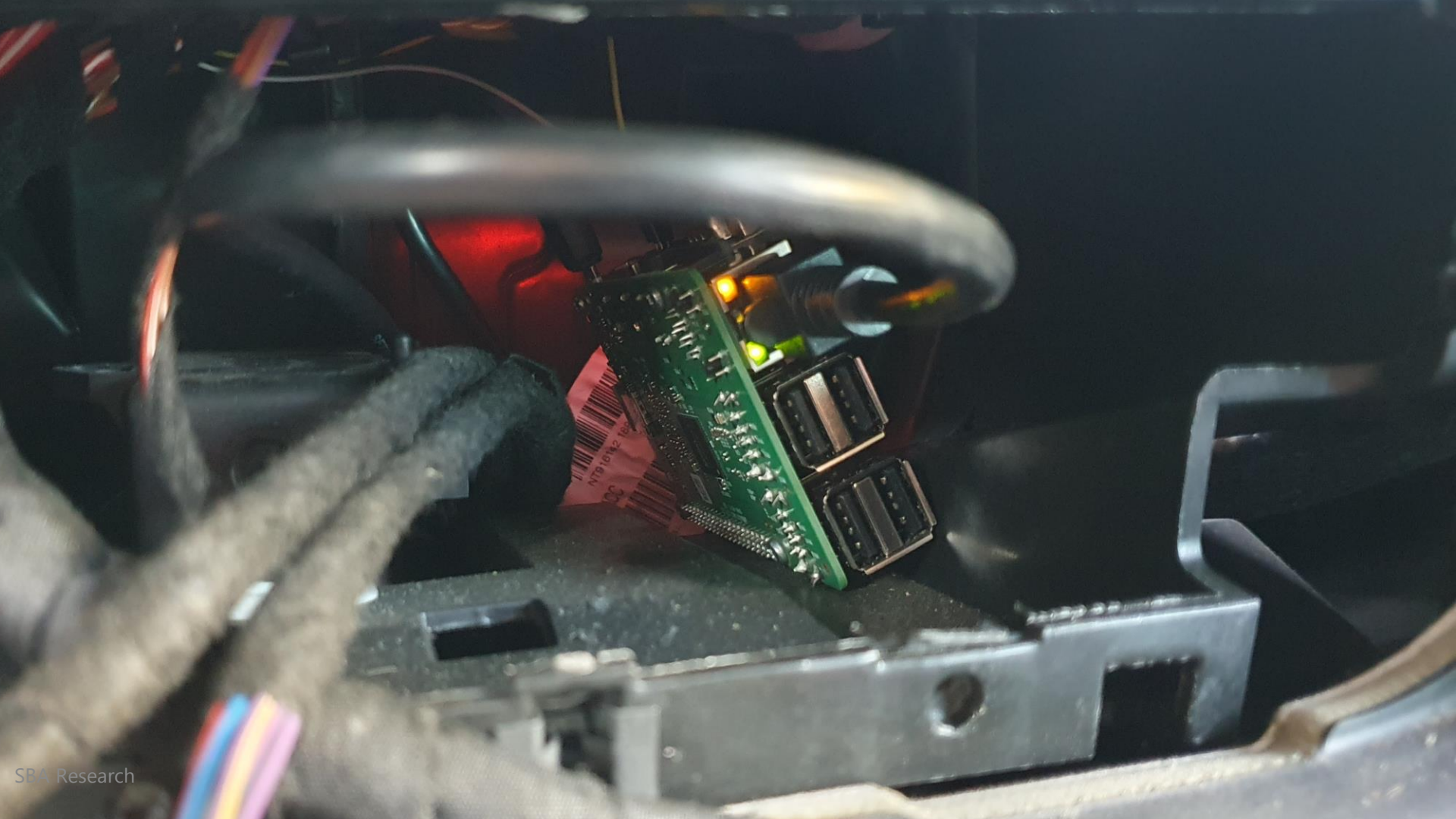
```
Terminal - sba@automotive-security: ~/embedded-container  
File Edit View Terminal Tabs Help  
(sba@automotive-security) - [~/embedded-container]  
$
```

```
Terminal - sba@automotive-security: ~/embedded-container  
File Edit View Terminal Tabs Help  
(sba@automotive-security) - [~/embedded-container]  
$ sudo crun run container2  
bck-i-search: sudo_
```

```
(sba@automotive-security) - [~/kitt]  
$
```

```
Terminal - sba@automotive-security: ~/embedded-container  
File Edit View Terminal Tabs Help  
(sba@automotive-security) - [~/embedded-container]  
$
```

```
Terminal - sba@automotive-security: ~/embedded-container  
File Edit View Terminal Tabs Help  
(sba@automotive-security) - [~/embedded-container]  
$ sudo crun run container2  
bck-i-search: sudo_
```





RADIO

MEDIA

PHONE



17:48



NAV

TRAFFIC

SETUP

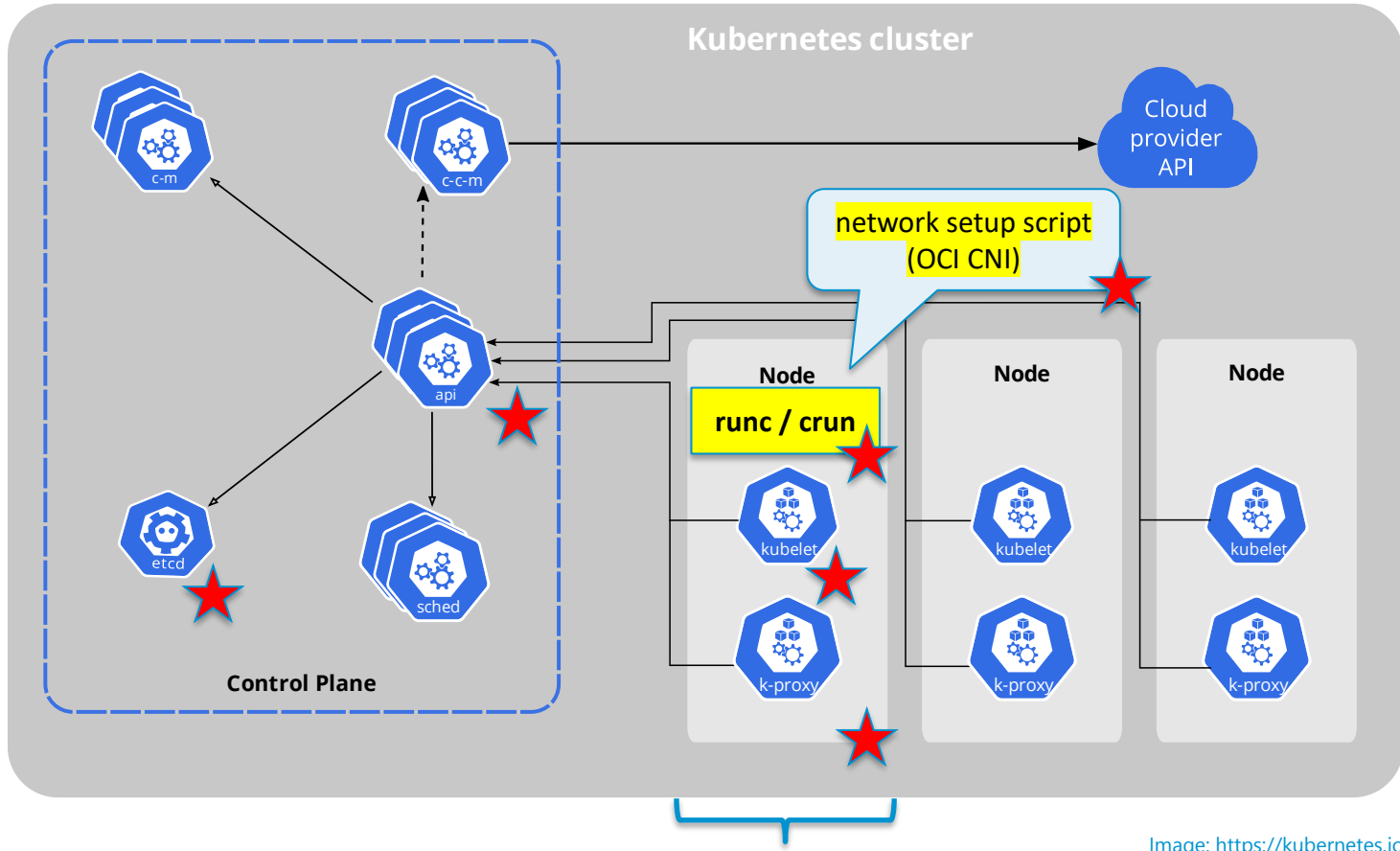
Extras










Speicher

Band



Is this safe?



- API server 
- Cloud controller manager (optional) 
- Controller manager 
- etcd (persistence store) 
- kubelet 
- kube-proxy 
- Scheduler 
- Control plane 
- Node 

Vulnerabilities (CVE+user config)

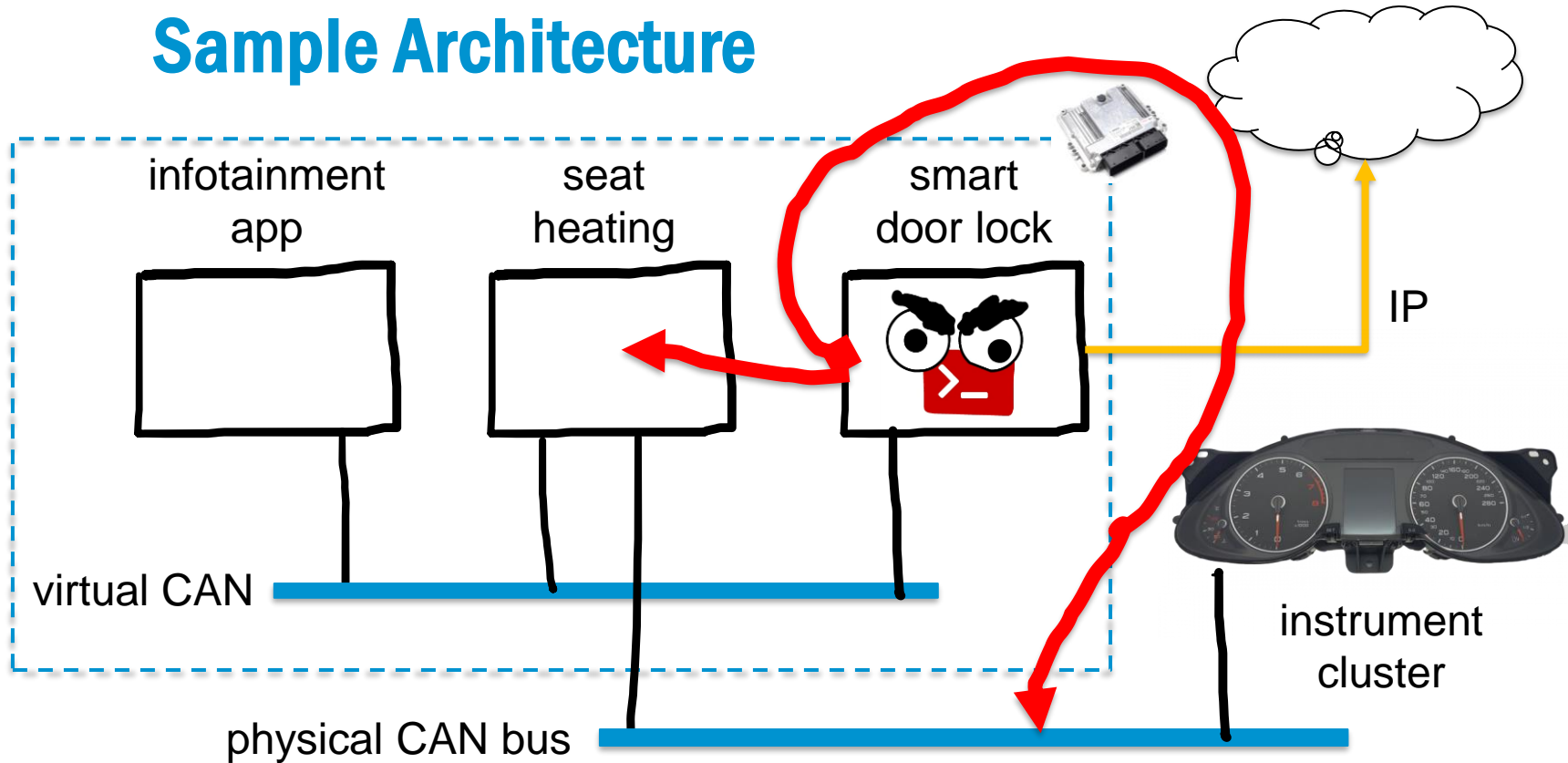
- CVE-2014-????: Symlink docker cp
- CVE-2015-{3627,3629,3630,3631}: docker config, Volume is insane
- CVE-2016-9962: File descriptor open in the root filesystem, /proc/\$pid/fd/\$n
- CVE-2018-15664: Path sanitisation, RENAME_EXCHANGE, LXD does it wierdly but good, Double check via proc
- CVE-2019-5736 18:00: /proc/self/exe, Reopen (O_RDONLY)
- CVE-2019-19921: Symlink exchange via VOLUME



/ # █



Sample Architecture



Future of Containers in Automotive („EDGE“)

- safety certified platforms
- software updates for fleets (for real)
- „zero-touch“ (over the air)
 - centralized configuration (pay-as-you-go)
 - centralized maintenance/updates
- DevOps for automotive applications

References and further reading

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- Can-utils
 - <https://github.com/linux-can/can-utils>
- CANalyzat0r
 - <https://github.com/schutzwerk/CANalyzat0r>
- Caring Caribou
 - <https://github.com/CaringCaribou/caringcaribou>
- Scapy CAN layer
 - <https://scapy.readthedocs.io/en/latest/api/scapy.layers.can.html>
- Raspberry Pi/PiCan 3 shield
 - <https://buyzero.de/products/pican-3>
- ICSim
 - <https://github.com/zombieCraig/ICSim>
- Automotive Security Research Group (ASRG)
 - <https://asrg.io/>
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